

	Hits	Search Text
1	3071	automat\$4 and (arm\$2 with gripper)
2	315	automat\$4 with (arm\$2 with gripper)
3	203	(automat\$4 with (arm\$2 with gripper)) and rotat\$5
4	976	automat\$4 with (arm\$2 with grip\$4)
5	233	(automat\$4 with (arm\$2 with grip\$4)) and (grip\$4 near4 rotat\$5)
6	216	(automat\$4 and (arm\$2 with gripper) and telescop\$4) and rotat\$4
7	4469	(422/63-67,300-304).CCLS.
8	1305	((422/63-67,300-304).CCLS.) and arm\$4
9	289	((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5
10	247	((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5) and rotat\$5
11	9	((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5) and rotat\$5) and telescop\$4
12	12	(automat\$4 or robot\$2) with (arm\$2 with gripper) with telescop\$3
13	120	(automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)
14	13	((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)) with arm\$2
15	45	((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)) and arm\$2

	Hits	Search Text
16	1498	(automat\$4 or robot\$2) with (arm\$2 with gripper)
17	93	((automat\$4 or robot\$2) with (arm\$2 with gripper)) and (drive near2 belt\$2)
18	4726	(901/1-9,14-29).CCLS.
19	543	((901/1-9,14-29).CCLS.) and gripper\$3
20	143	((901/1-9,14-29).CCLS.) and gripper\$3) and belt\$2
21	2023	two near2 grippers
22	49	(two near2 grippers) near4 drive\$2
23	104	(robot\$4 or automat\$4) and (telescop\$3 near3 height near3 adjust\$5)
24	61	((robot\$4 or automat\$4) and (telescop\$3 near3 height near3 adjust\$5)) and arm\$2
25	117	(robot\$4 or automat\$4) and (telescop\$3 near3 height) and arm\$2
26	441	(automat\$4 or robot\$2) with ((shaft\$2 or rail\$2 or arm\$2 or height) near3 telescop\$3)
27	95	((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2 or arm\$2 or height) near3 telescop\$3)) and height
28	2	("5215377").PN.
29	9	grippers near4 independent near3 drive\$3
30	1098	grippers near4 drive\$3

	Hits	Search Text
31	75	(grippers near4 drive\$3) with arm\$2
32	241	((two or pair) near2 grippers) with arm
33	18	((((two or pair) near2 grippers) with arm) with (belt or drive\$2)
34	2	("6652015").PN.
35	289	((plural\$4 or two or couple or pair) near2 grippers) with arm
36	6	((("6,080,363") or ("5948159") or ("5,417,123"))).PN.
37	15	"2196428"
38	3	"GB 2196428"
39	2	("4738824").PN.
40	2	("5,895,628").PN.
41	1009	automat\$4 with (arm\$2 near6 (hand\$2 or finger\$3 or gripper\$2))
42	192	(automat\$4 with (arm\$2 near6 (hand\$2 or finger\$3 or gripper\$2))) with (free or rotat\$4 or "X-Y-Z")